

Realistic and Interactive Simulation of Rivers

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Motivation

- Interactive physically-based simulation of water flowing on a terrain
 - Quick flow analysis
 - Simulator environments
 - Games
- Challenges
 - Simulation
 - Full particle interaction
 - Surface extraction
 - Fast processing
 - Static memory footprint
 - Explicit representation



Smoothed particle hydrodynamics

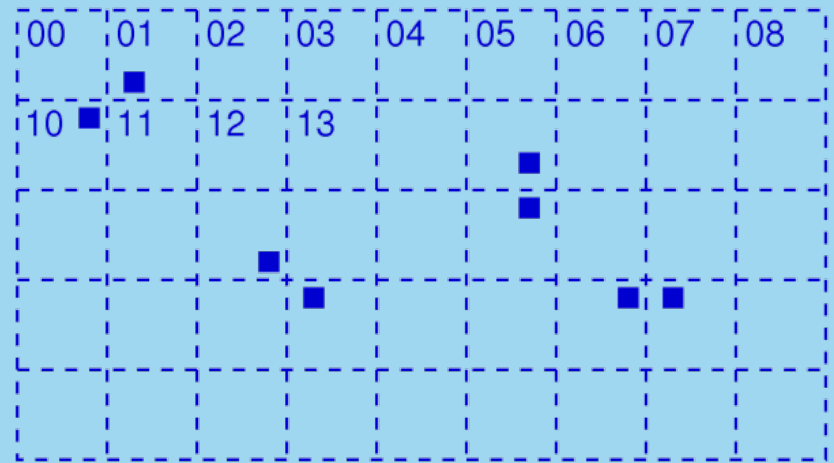
- Lagrangian approach for fluid dynamics [Müller2003]

$$A_S(\vec{r}) = \sum_j m_j \frac{A_j}{\rho_j} W(\vec{r} - \vec{r}_j, h)$$

- Interpolate quantity A using smoothing kernel W
- Particle neighborhood queries
- Hierarchical search methods
- Octree-based approach [Vemuri1998]
 - Linear complexity if bin size = 2*(max. particle diameter)
 - Dynamic memory allocation necessary
 - Sensitive to particle count and density

Neighborhood by linear search

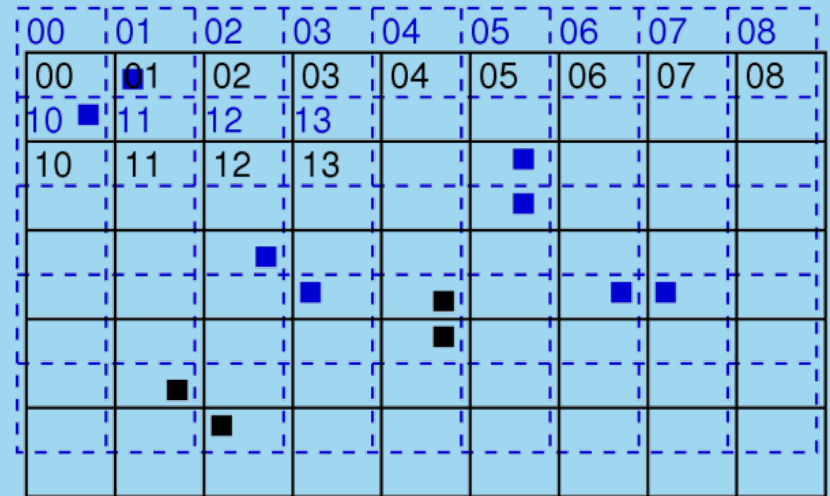
1. Quantize domain to bins
2. Build particle id from bin numbers: $0|i_z|i_y|i_x$
3. Sort according to id
4. Collide with all left neighbors until $id \leq (id_{self} - 2)$



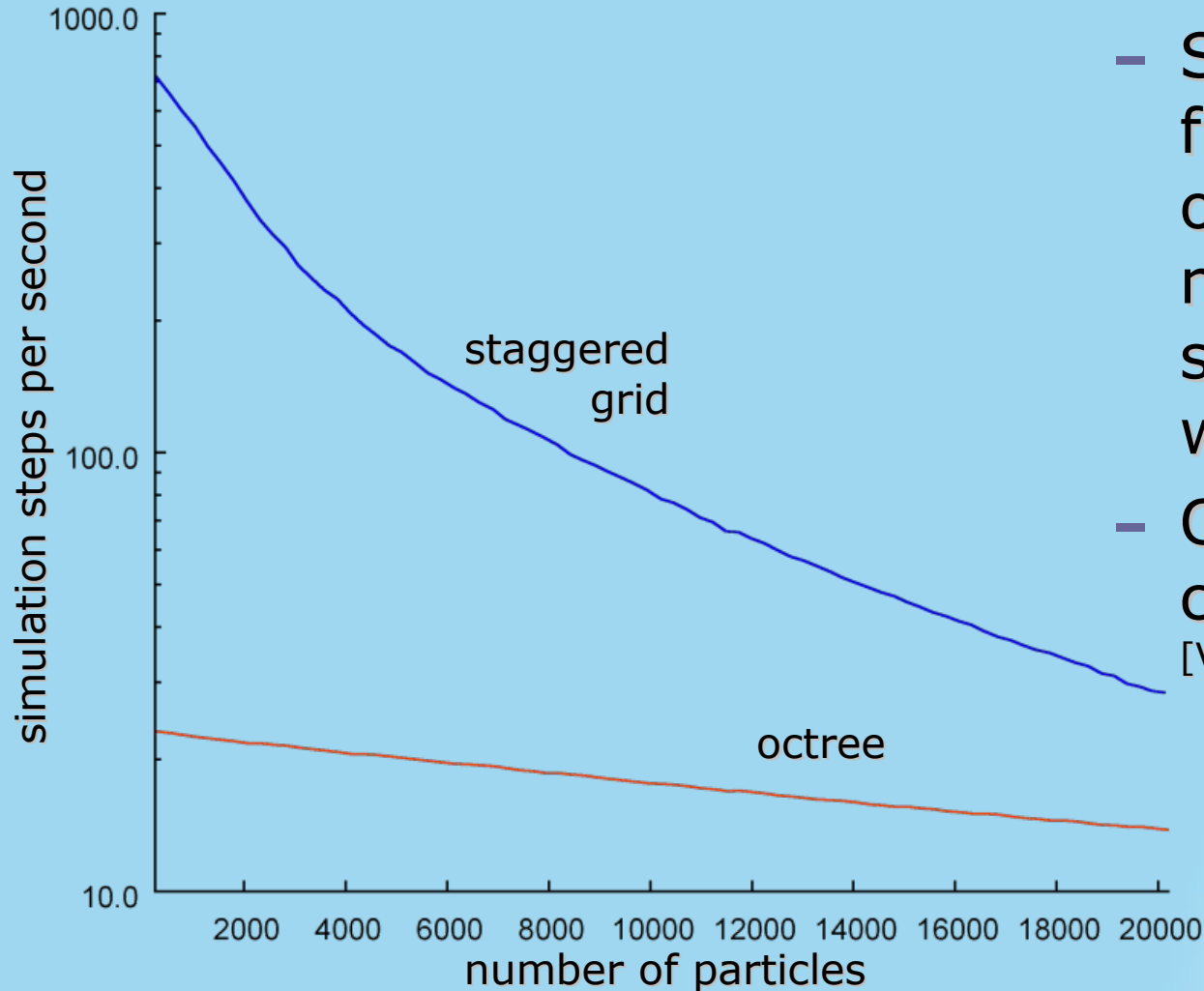
- Cache efficient
- Linear time complexity for traversal
- Sort complexity $O(n \log n)$

Staggered grid

- For arbitrary dimensions
 - Add one staggered grid for every missing dimension
 - Use leading bit per dimension processed to avoid redundant collisions
- Finds all neighbors
- Linear traversal
(fixed bin and fixed max. particle size)
- Static memory footprint
- Insensitive to particle count and density



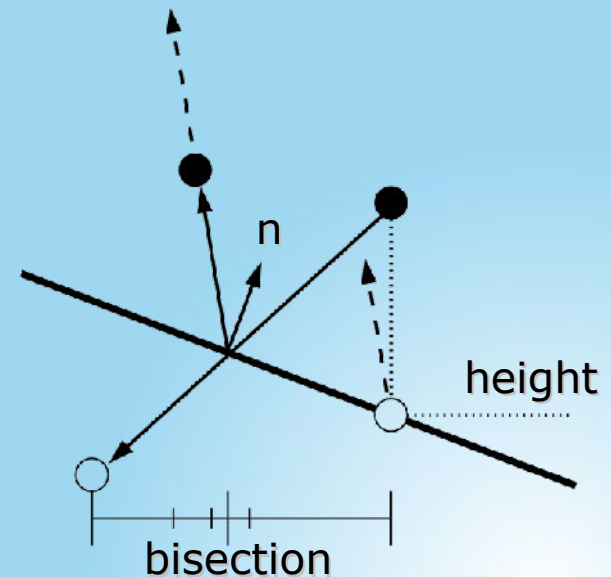
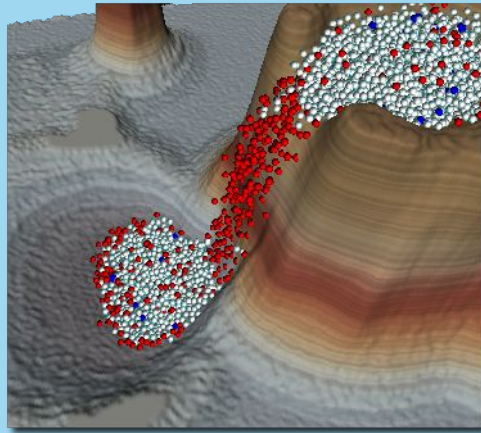
Performance



- Staggered grid is faster by an order of magnitude for sparse systems we target
- Octree has huge constant factor [Vemuri1998]

Optimized collision resolution

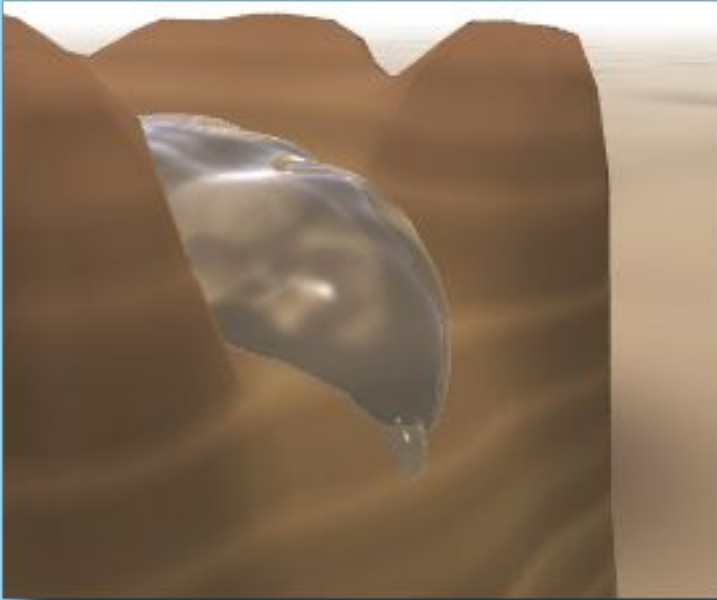
- Introduce „frozen“ particles
 - Exclude from terrain collision
- Precision terrain collision avoids motion artifacts
 - Iterative backtracking of motion path (bisection)
 - Inelastic bounce using surface parameters
 - Recompute path length accounting for velocity damping of collision



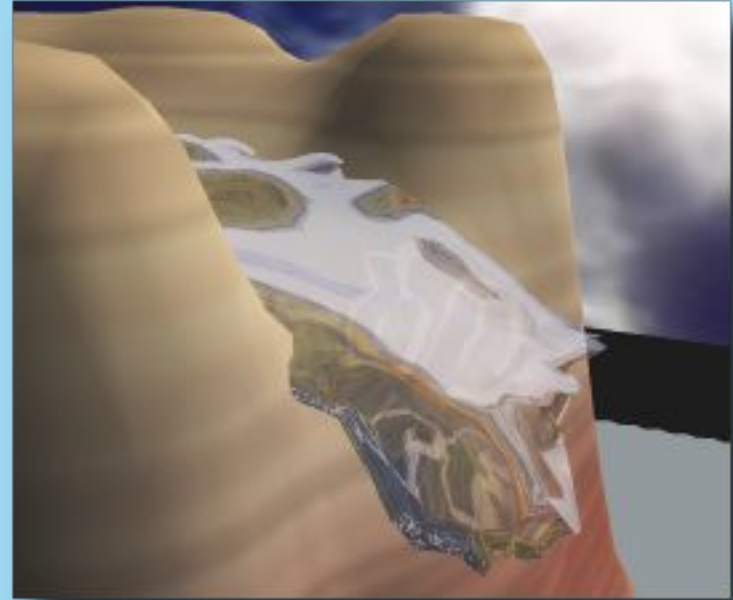
Surface extraction

- Marching cubes or raycasting
 - Construct fluid free surface as level set of particle radii
 - Very high tessellation / small integration step size needed for detail
 - High memory requirements / sampling artifacts
 - Incremental update very difficult: no GPU storage
- Point splatting
 - Fast
 - Dense particle set needed
 - No explicit surface representation
 - High quality splats (surfels) need additional data per particle

Appearance



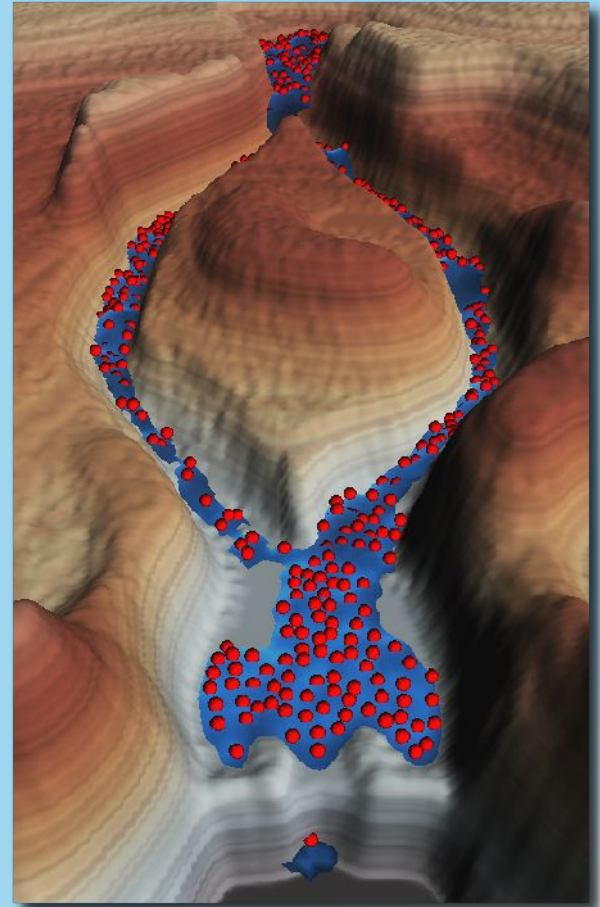
raytraced surface



carpet surface

The carpet

- Interactive display
 - Visualize every simulation step
- Sparse particle set
 - Closed surface
- Large terrains
 - Generate only where particles are
- Explicit surface representation
 - Advanced rendering shaders
- Split / join handled automatically



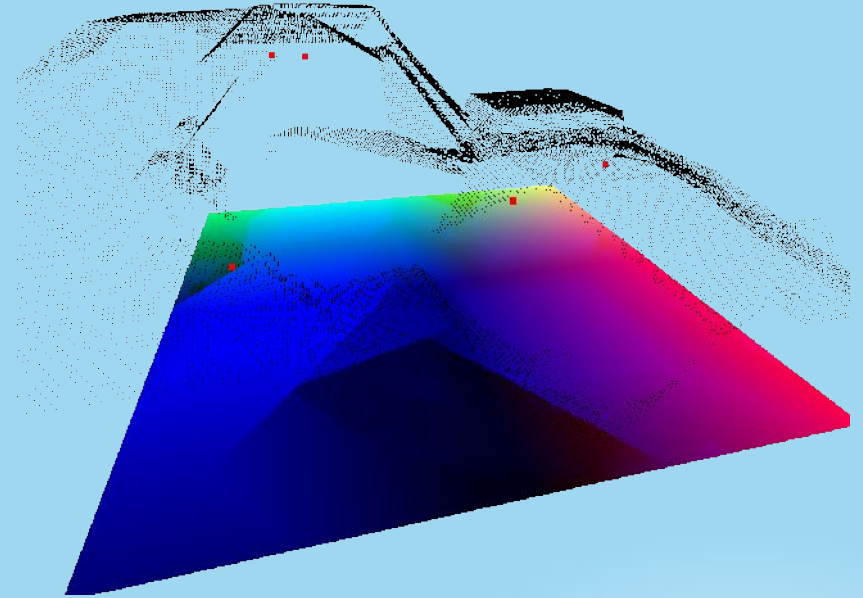
CPU carpet construction

1. Store all particles in quadtree leaves
 2. Pull particle height up the tree using max operation
 3. Top-down traversal to leaf
 - a) render quad
 - b) accelerate position downwards
- Constant memory footprint
 - Linear complexity
 - Multi-threaded
 - Step 1 folded into advection



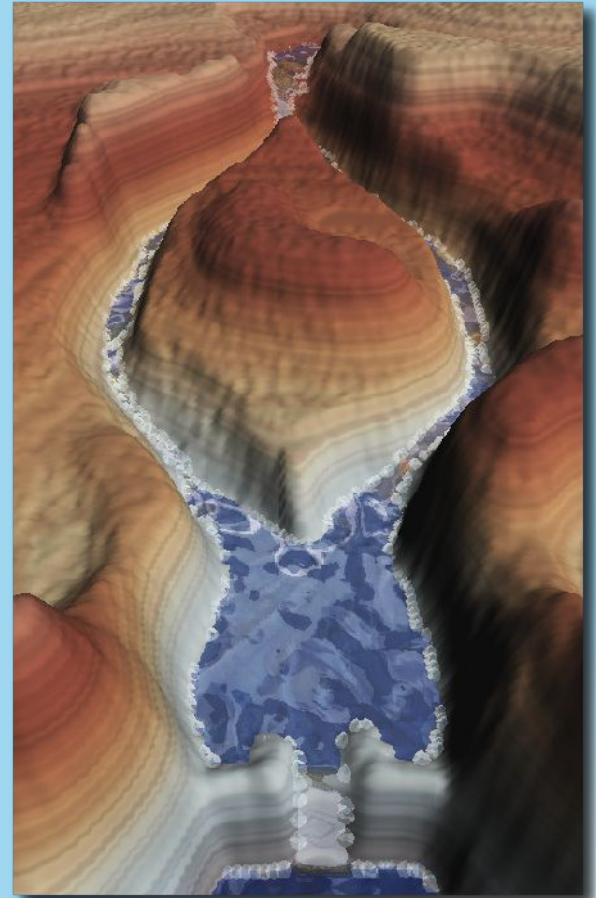
GPU carpet construction

1. Create z-image and apply gravity to carpet vertices
 2. Splat particles to depth image with z-test on
 3. Render vertex array as triangle strip
- Minimal data upload
 - Incremental update
 - Provide shape for particle using oriented depth sprites
 - Efficient rendering possible (early z-test)



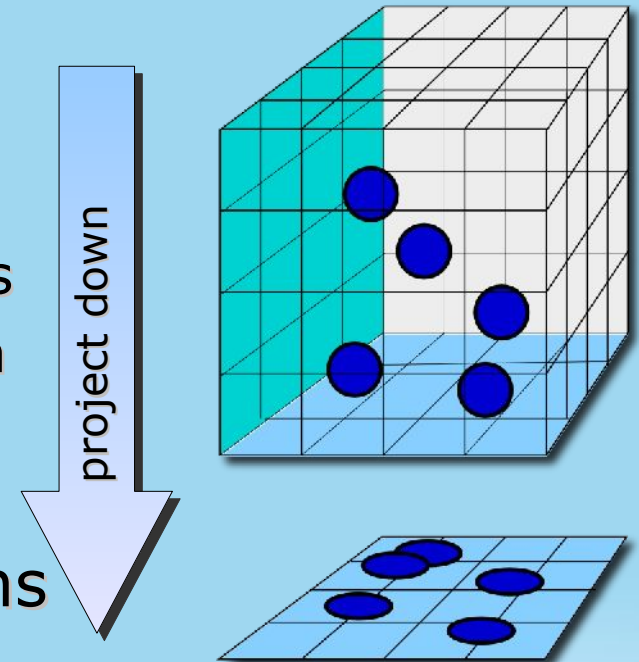
Carpet rendering

- Augmented rendering by using provided per vertex information
 - Flow direction
 - Local speed
 - Water depth
- Surface waves / wind
 - Procedural gravity update
- Influence simulation
 - Terrain surface adhesion
 - Friction modulation („Wet map“)
 - Erosion

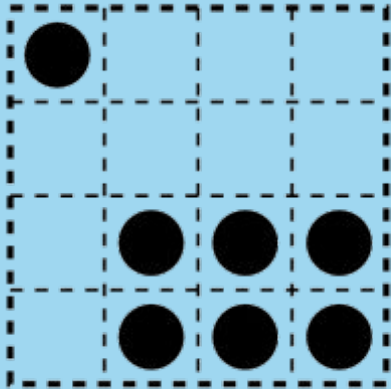


Carpet optimization

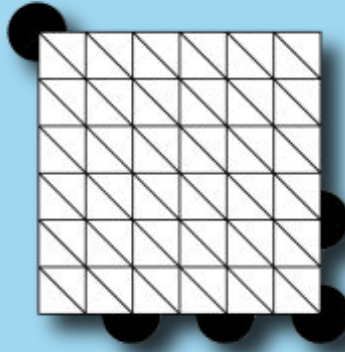
- High resolution carpet or very large terrain
 - Truncate quadtree
 - Leaves contain a set of carpet bins
 - Projection is very simple (mask on particle id)
- Store resulting surface of pre-computed particle configurations
 - High quality surface tension
 - Different rendering primitives for isolated parts
 - LOD



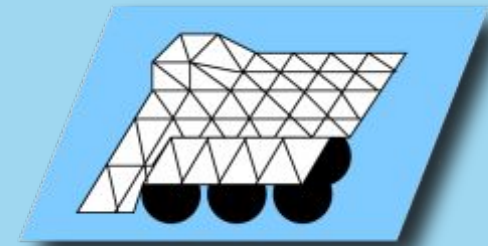
Configuration examples



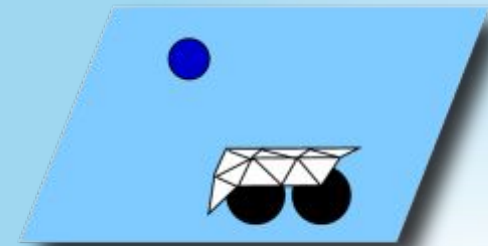
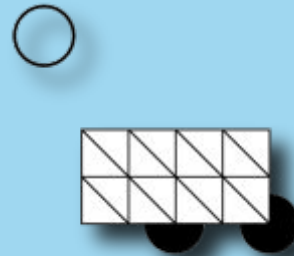
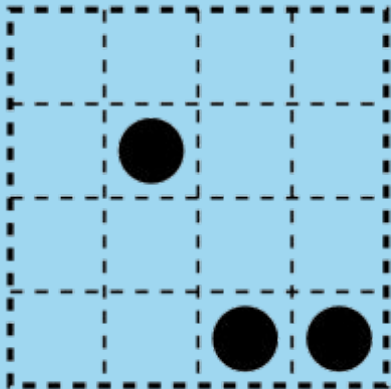
projected
configuration



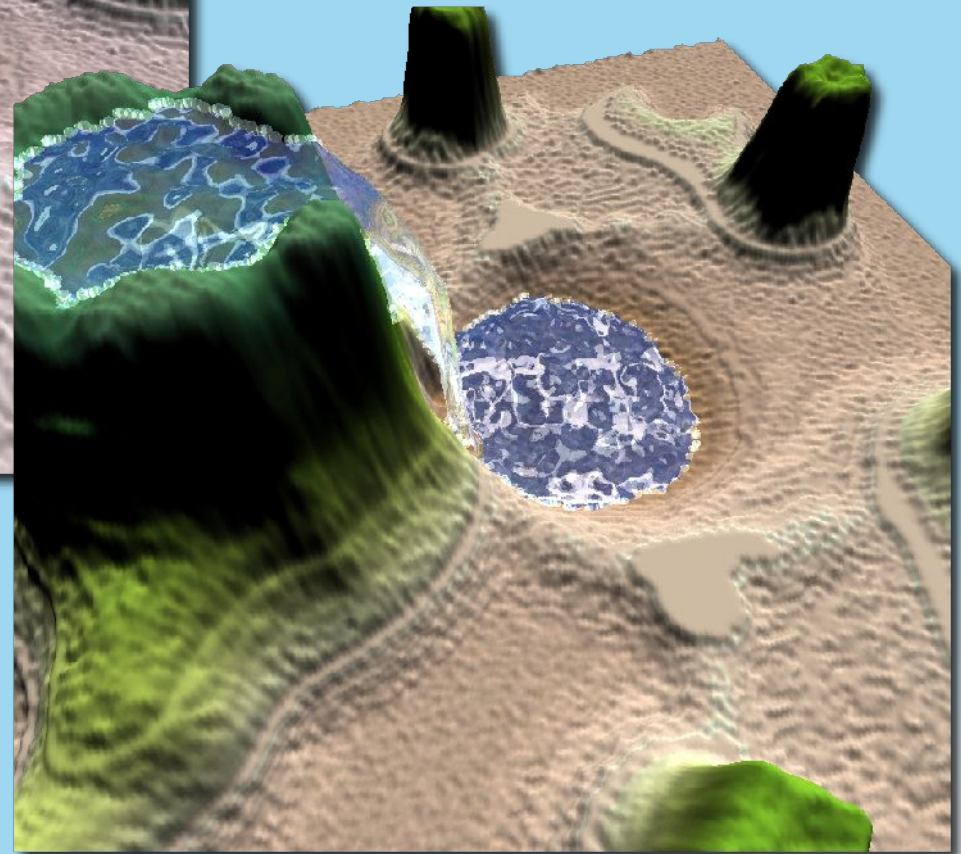
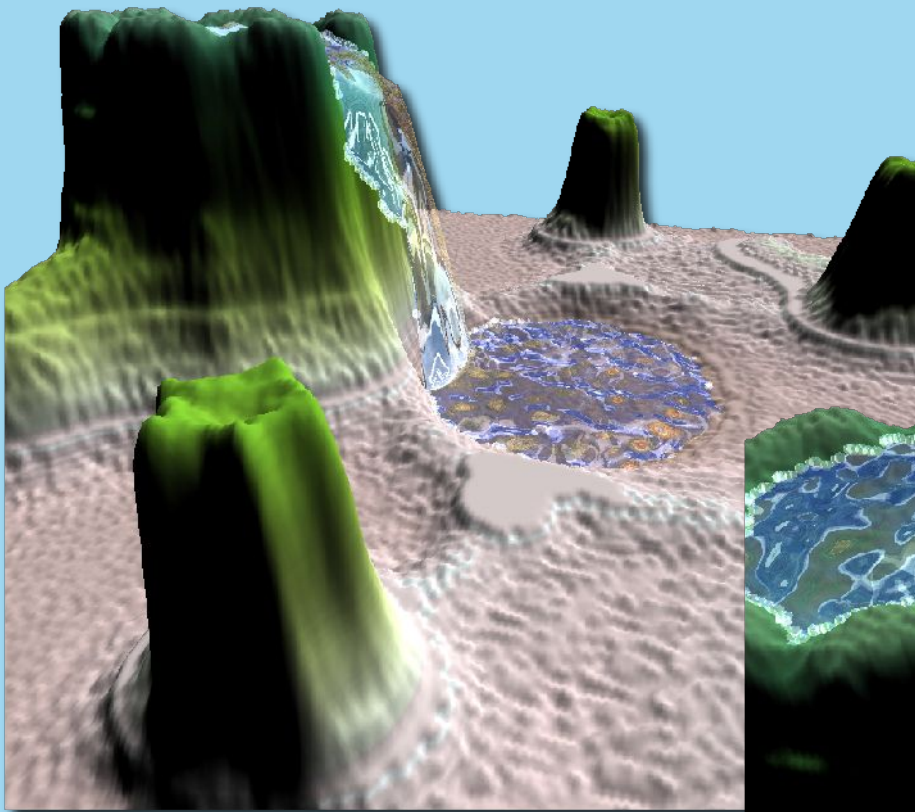
dual carpet
quadtree mesh



rendered carpet
(side view)

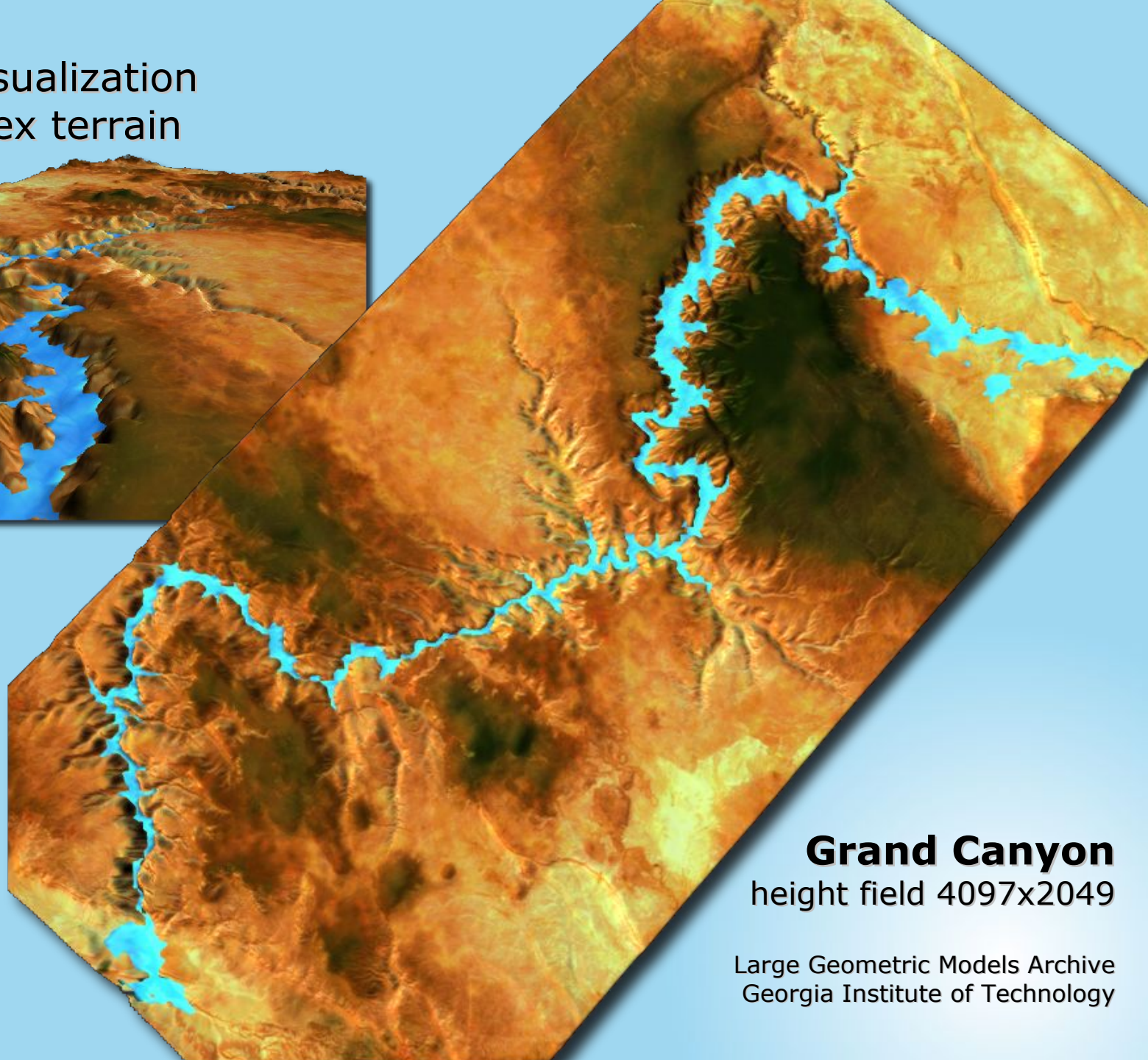
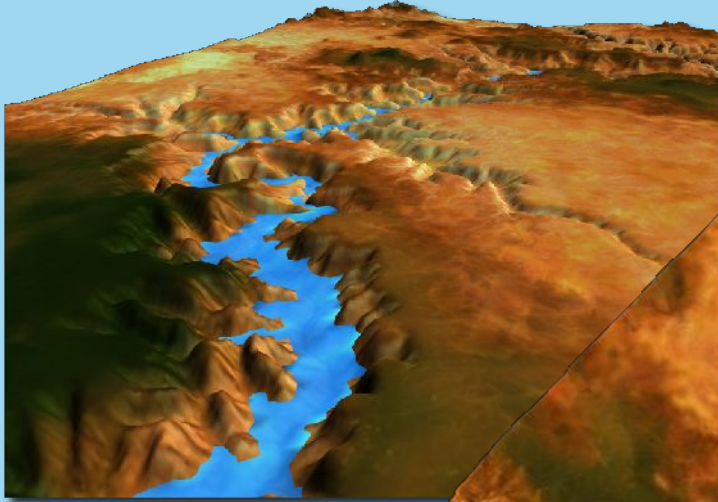


Carpet visualization
for real-time applications
in extreme cases



68 fps
3.000
particles

Carpet visualization on complex terrain

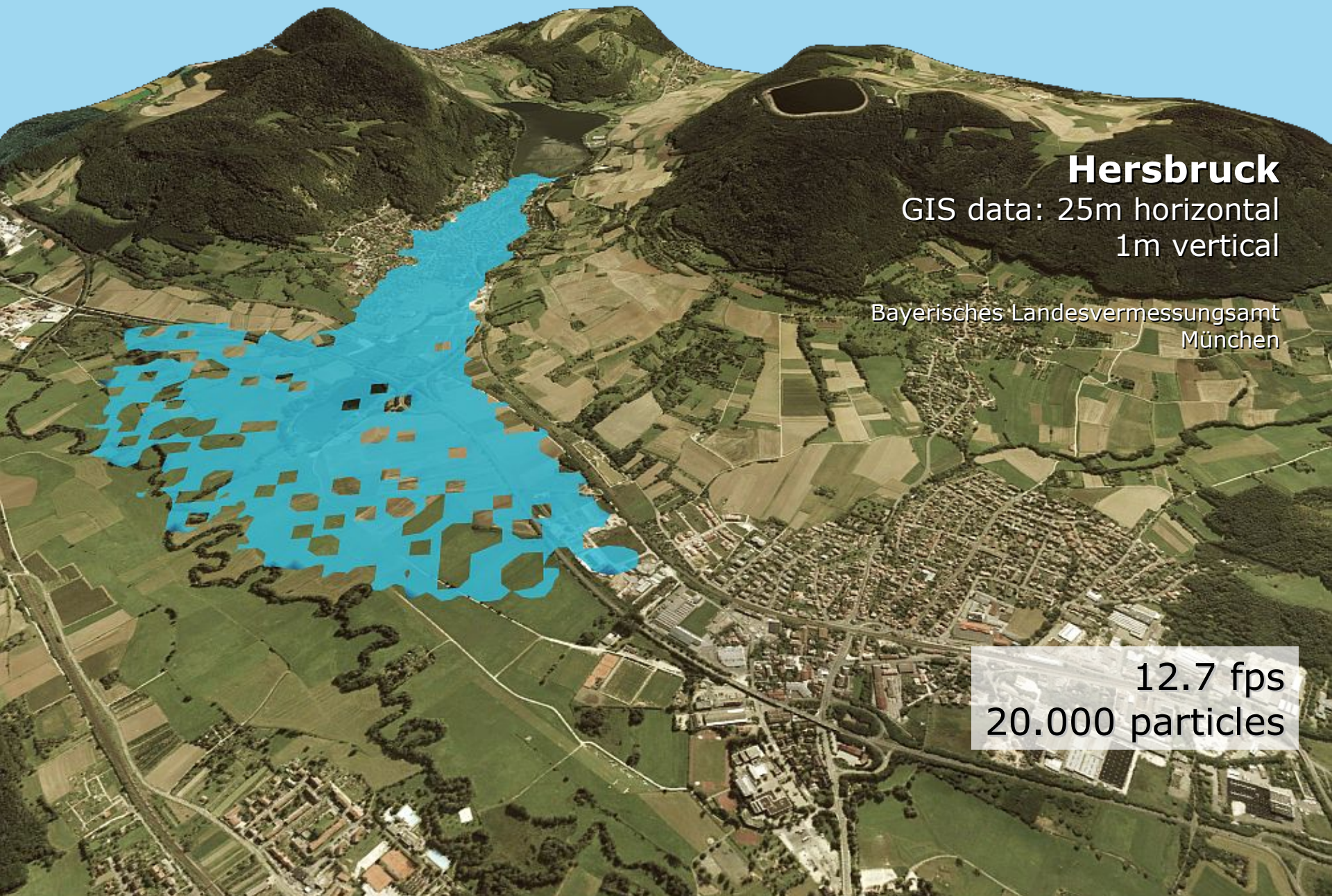


26 fps
8.000
particles

Grand Canyon
height field 4097x2049

Large Geometric Models Archive
Georgia Institute of Technology

Carpet visualization for environmental simulation



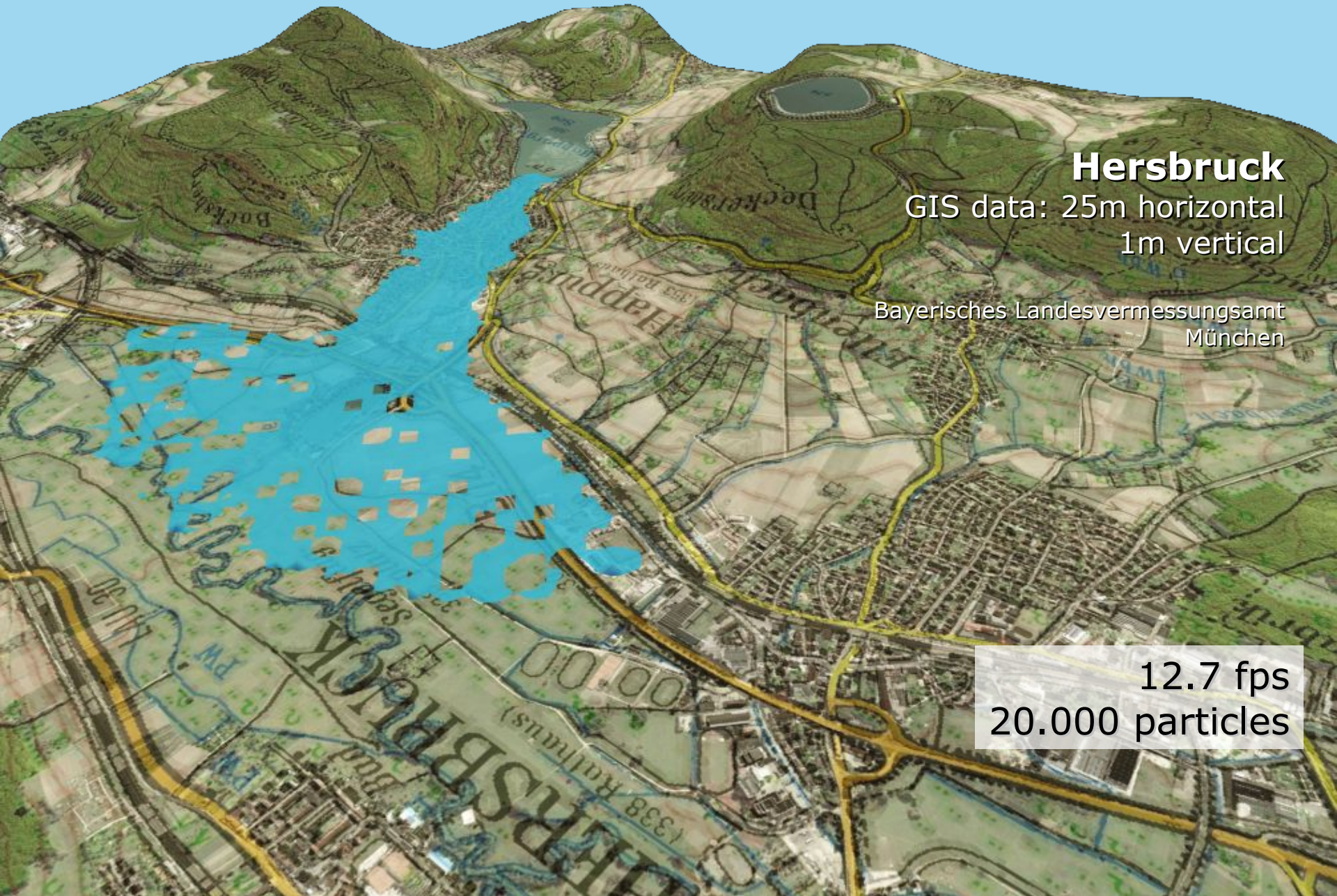
Hersbruck

GIS data: 25m horizontal
1m vertical

Bayerisches Landesvermessungsamt
München

12.7 fps
20.000 particles

Carpet visualization for environmental simulation

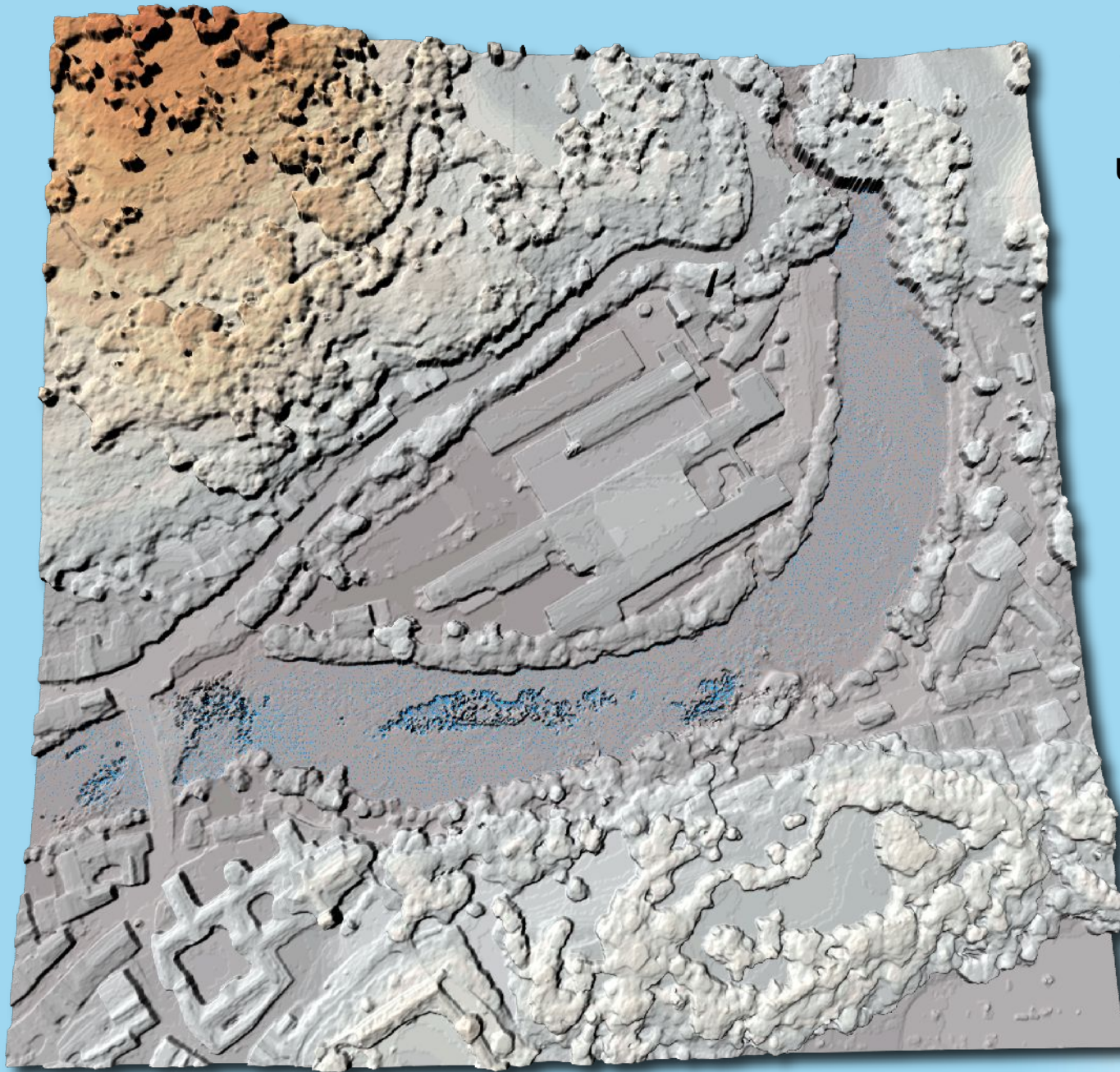


Hersbruck

GIS data: 25m horizontal
1m vertical

Bayerisches Landesvermessungsamt
München

12.7 fps
20.000 particles

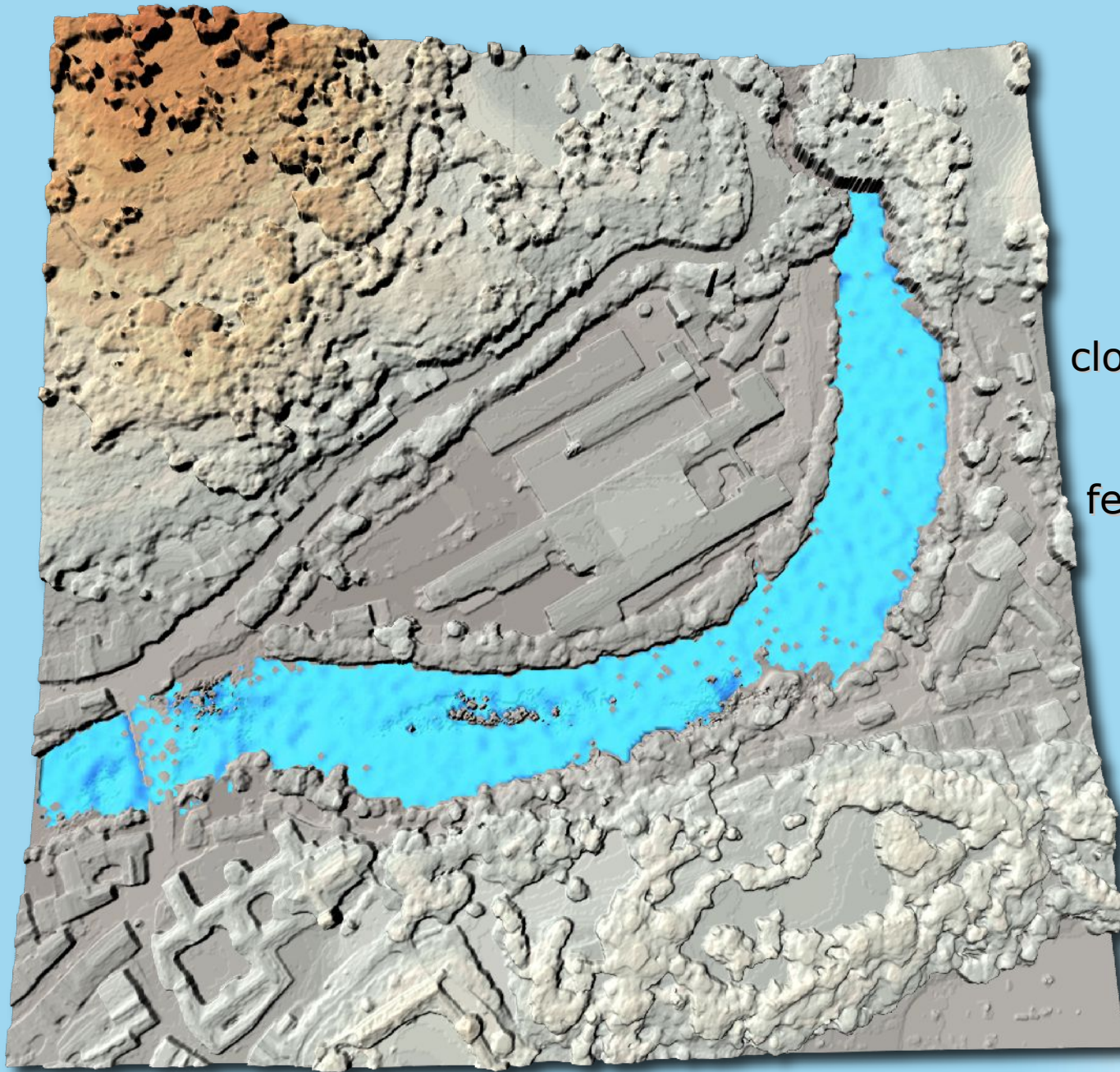


Instant visualization
and simulation on
ultra-high resolution
scan data

HRSC camera data
from single-pass
overflight

Resolution:
15 cm horizontal
10 cm vertical

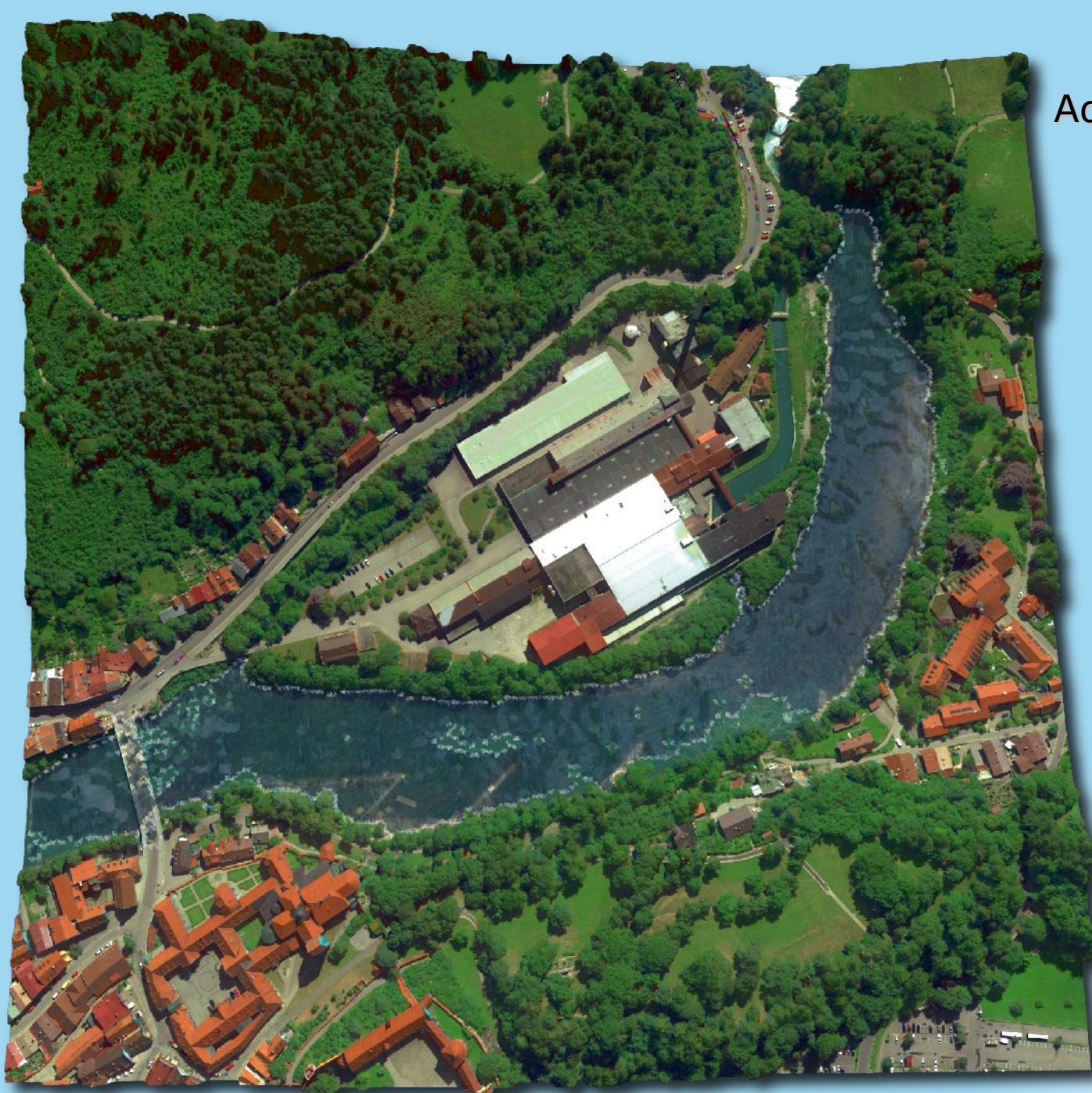
German Aerospace
Center (DLR)
Institute of Robotics
and Mechatronics



Highly interactive
simulation of river
behavior

Carpet provides
closed surface despite
sparse particle set
without hiding flow
features or obscuring
terrain detail

German Aerospace
Center (DLR)
Institute of Robotics
and Mechatronics



Add textures using
the chromatic
HRSC channels

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and Mechatronics

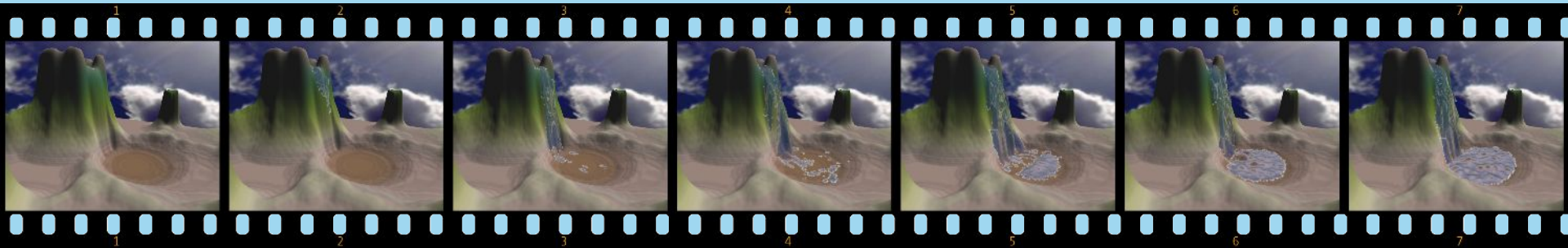
21 fps
9.500 particles

Füssen
HRSC scan
15 cm horizontal
10 cm vertical



German Aerospace
Center (DLR)
Institute of Robotics
and Mechatronics

Video





**Thanks for listening !
Questions ?**

Demo + Infos

**[http://www.cg.in.tum.de/Research/Publications/
RiverSim](http://www.cg.in.tum.de/Research/Publications/RiverSim)**